

Calculation, Design and Manufacturing of Mobigym

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Abstract:- Bicycles was invented in 1817, first means of transport for public ease & bicycle also provides numerous health benefits by rigorous body & as well environmental healthy i.e. pollution free excess to road. Gymnasium, a place where people do heavy workout and gain fitness with proper muscular body. Mobigym, a concoction of bicycle and gym put's both of them together. Mobigym is a bicycle designed for exercise purpose and can be used as means of transport.

Same in traditional bicycles the rear chain drive mechanism is carried out by foot pedals connects the rear wheel of cycle and another chain drive mechanics introduced carried by the handle connects the front wheel of the bicycle. Simultaneous action burns lots of calories and also bicycle cum mobigym is increased. Key factor of this mobigym is that it is being comfortably being designed for both men and women. Mobigym might be the need for fitness freak.

I. INTRODUCTION

In today's scenario, the life of people is becoming fast and growing in a very sensible manner where people do not get time for their personal body work out and hence they grow in a very unhealthy environment. Hence, we provided a very low cost and affordable equipment for a particular persons whole body workout in a only one equipment that we named mobigym.

Mobigym the name itself tells about all that we provided as a solution for whole body exercises .In this kind of equipment a person cannot even ride the bicycle through pedaling by legs but can also ride by using hand motion i.e the motion can provide the exercise to the arms, chest, back and also to the shoulder of a particular human riding the bicycle .

Using this equipment for a body workout people have a freedom to workout according to their free time and According to science, body of a particular human being grows in a better way doing a workout in an open environment rather than closed room and shifting from machine to machine.

II. PROBLEMS IDENTIFIED

Working out at same place may be problematic for some people.

- Due to busy work schedule people are not able to workout efficiently.
- Indoor exercises are not much fruitful as green environment exercises.
- Only one person can use gym on a single membership card.
- You have to wait for your turn in gym for working out on a particular equipment.
- Today's reality is that people want a good physique but they don't have sufficient time to give to gym.

V. SOLUTION FOR PROBLEMS IDENTIFIED

- Mobigym allows the person to workout in healthy environment.
- Occupies less space as compared to gym equipments.
- Provides good physique to a person & travelling medium as well.
- It also provide environment friendly travelling medium.
- No trainer is required i.e simple to drive
- Unlike gym no membership is required anybody can use it whenever one is willing.
- While driving both the mechanism simultaneously arm, thighs, back and shoulder exercise are being carried out
- Economical and one time investment

VI. PROPOSED DESIGN

A. Introduction

The mobigym is not just a bicycle but it is a complete kit for fitness of a particular person providing not only the exercise to the body but can also help the person to reach from source to destination. Mobigym allows many types of freedom to the people like if a person joins a gym for their fitness they need to take membership and they need to listen to the trainer as well, after that they are getting used to with the gyming equipments and for that at some time the need to wait till other person complete his exercise. In mobigym there is no kind of restriction, any person of the family can use it and at any time whichever they think is suitable for them.

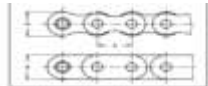
Mobigym is also a bicycle which helps to develop various muscles of the body at a time and only in just one equipment. It can be used by pedalling not only through legs but also using the arms as well.

B. Calculations of the Model:

Chains:

Fig 4

6 links Roller Chains



British Standard Chains

Series	Description	ISO 6061 No.	Pitch (p)	Width (b)	Roller diam (d _r)	Pin diam (d _p)	Pin length (l _p)	Rolling load (F _r)	Weight (W)	Breaking load (F _b)
05B	1/2" x 5/16"	05B-110	12.7	12.7	12.7	12.7	12.7	1.10	0.10	11.00
06B	5/16" x 3/8"	06B-150	15.875	15.875	15.875	15.875	15.875	1.50	0.15	15.00
08B	3/8" x 1/2"	08B-200	20.625	20.625	20.625	20.625	20.625	2.00	0.20	20.00
10B	1/2" x 5/8"	10B-275	27.0	27.0	27.0	27.0	27.0	2.75	0.275	27.50
12B	5/8" x 3/4"	12B-350	34.925	34.925	34.925	34.925	34.925	3.50	0.35	35.00

Single chains to DIN 8187, V-belt standards

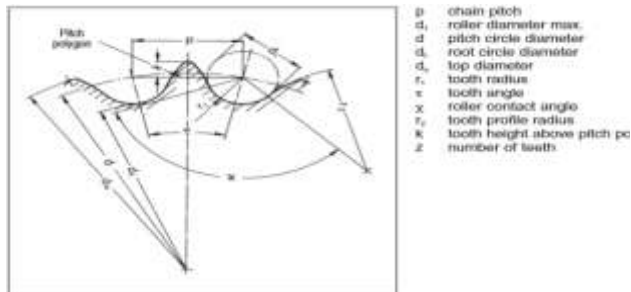


Fig 5

- Design calculation for pinion

- Speed of pinion(N_g) = 100rpm
- Velocity ratio =2
- Mass of rider (m)= 60kg
- Length of pedal lever(L) =190mm
- Assume british standard chain G52 iwis designation : pitch(P)-8mm, width(b1) =3
- Step1) Maximum torque applied on bicycle = (Mass of rider x g)x length of the pedal lever = 60x9.81x0.1=58.86 N-m.
- Step2) Calculate rated power PR= 2πNT/60 = 2πx100x58.86/60

$$= 0.616KW.$$

- Step3) Design Power Pd= PRxKL
Where, load Factor KL =1.25

$$Pd = 0.616 \times 1.25$$

$$= 0.77KW.$$

- Step4) Tangential ortooth load
F_t= Pd/V_p.

$$\begin{aligned} \text{Where, } V_p &= (\pi \times D_p \times N_p / 60000) \\ &= (\pi \times 16m \times 200 / 60000) \\ &= 0.617 \text{ x m} \end{aligned}$$

$$\text{Therefore, } F_t = (0.77 \times 10^3) / (0.167 \times m)$$

$$t = (4.61 \times 10^3) / (m).$$

- Design of Chain And Sprocket
d=5mm

- Pitch circle diameter
dp= P/sin(180/T)
P= 8mm,T=42,
PCD=107.051mm

- Root Circle Diameter
df=d-d1
= 107.051-5
= 102.05mm

- Top Diameter
(d_a)_{max}=d+1.2P-d₁
= 107.051+(1.25*8)-5
= 112.05mm

$$\begin{aligned} (d_a)_{\min} &= d + (1 - 1.6/T)P - d_1 \\ &= 107.051 + (1 - 1.6/30)8 - 5 \\ &= 101.891 \text{ mm} \end{aligned}$$

- Tooth Height
K_{max}=0.625P-0.5d₁+((0.8/T)P)
Fig 9:Isentropic View

$$= 2.625 \text{ mm}$$

$$K_{\min} = 0.5(P - d_1)$$

$$= 0.5(8 - 5)$$

- Tooth Space
 $R_{min}=0.505d_1+0.064*\sqrt{d_1}$
 $=2.63\text{mm}$

- Roller Contact
 $X_{min}=120^\circ-(90^\circ/42)$
 $=117.85^\circ$
 $X_{max}=140^\circ-(90^\circ/42)$
 $=137.85^\circ$

- Tooth Profile Radius
 $R_{2max}=0.008d_1(T^2+180)$
 $=77.76\text{mm}$

- Tooth Width
 $=0.93b_1$
 $=2.938\text{mm}$

- Beam Strength
 $F_B=S_o*CV*Y*b*m(1-b/L)$
 Where, $S_o=105\text{Mpa}$
 $CV=0.5$
 Y = Lewis Factor For pinion,
 $Y_p = 0.45 - (2.87 / (t_f)_p)$
 $= 0.45 - (2.87 / 18)$
 $Y_p = 0.29$
 For Gear:

$$Y_g=0.45-(2.87/(t_f)_g)$$

$$=0.45-(2.87/72)$$

$$=0.4451$$

B =phase width of gear =7 x m

Now for pinion,

$$Sop=(S_o \times Y)_p$$

$$=105 \times 0.3255 = 34.17$$

For Gear,

$$Sog=(S_o \times Y)_g$$

$$=105 \times 0.4451 = 46.73$$

$$F_B=34.17 \times 0.5 \times 7\text{m} \times \text{m} \times (1-7\text{m}/17.88\text{m})$$

$$= 72.53 \times \text{m}^2$$

By limiting condition $F_B = F_t$

$$72.56\text{m}^2 = (4.61 \times 103)/\text{m}$$

$$\text{m} = 1.87$$

$$\text{Tangential load } F_t = (4.61 \times 103)/\text{m}$$

$$= 253 \text{ N}$$

- Pitch Velocity $V_p = 0.167 \times \text{m}$
 $=0.167 \times 1.87$
 $= 0.312 \text{ m/s.}$
- Diameter of pinion $D_p=16 \times \text{m}$

$$=16 \times 1.87$$

$$=29.92\text{mm}$$

- Diameter of Gear $D_g=32 \times \text{m}$
 $=32 \times 1.87$
 $=59.84\text{mm}$

Design Of Bearing:

Equivalent load coming on bearing,
 T xiii-xiv (B.D.Shiwalkar Data Book)

$$F_e=(x F_r + y F_a)k_\square \times k_0 \times k_p \times k_f$$

F_r =Radial load

F_a =Axial load

$$F_r=253.63\text{N}$$

$$F_a=253\text{N}$$

From T-xiii-14,



$$F_a/F_r=0.99 > e$$

$e=0.25$ (For deep grooved ball bearing)

$$X=0.56 \text{ \& } Y=1.6$$

From T-xiii-15

Service Factor=2.5(heavy shaft load ball bearing)

$$F_e=((0.56 \times 253.63) + (1.6 \times 253)) \times 2.5 \times 1 \times 1 \times 1 \times 1$$

$$=1367.082\text{N}$$

Life of Bearing:

From T-xiii-17

$$L=4000-8000\text{hrs}(\text{domestic machines})$$

$$L=8000\text{hrs}$$

$$L=(c/F_e)^n * k_{ret}$$

$$n=3 \dots\dots\dots (\text{For ball bearing})$$

k_{ret} = reliability factor (T-xiii-15)

For 90% reliability, $k_{ret}=1$

c=specific dynamic for ball bearing
 $8000=(c/1367.082)^3*1$

C=27341.64

From T-xiii-21

C=27500

Hence, selecting bearing 0210.

C. Design of Mobigym .



Fig 6: Front view



Fig 7: Top View

Fig : Side View

- **Analysis Of Mobigym**

Fig10: Analysis Of Mobigym

Impulse Momentum=(M*(V₁-V₂)/T)

Where, M=mass of Bicycle and rider =100kg

V₁=Initial Speed of bicycle = 40Kmph.

V₂=Final Speed of bicycle = 0Kmph

T =Impact time = 1second

Therefore,

Impulse Momentum=(100*(40-0)/1)
 = 4000N

- **Original View of Mobigym:**

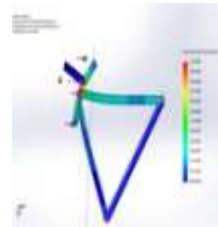


Fig 11: Original Product

D. Ergonomis:

Ergonomics of a bicycle refers to a pain-free & comfortable ride. Cycling right is just a matter of adjustments. On a bicycle the whole body is in action, many muscles are involved & each muscle has its counterpart. All the forces need to balance out before you begin to experience the true riding comfort.

PROBLEMS:

HANDS

hurts because : The arms are straightened.

The torso & arms are at an unfavorable angle. The handle bar and grip are not optimally shaped.

BUTTOCKS

hurts because : The saddle is positioned too high above the crank. Distance between the saddle and the crank is not right.

Saddle is at wrong angle.

KNEES & FEETS

hurts because : The saddle is too low.

The foot is wrongly positioned on the pedal.

The shoe is uncomfortable or tightly laced. The selected gears are too heavy for that particular terrain.



VIII. CONCLUSION

From the research work done we came to conclusion which are as follows:-

1. Chain drive are less in weight as compared to shaft drive bicycle.
2. Safety of the human is more important aspect in man machine relationship.
3. Anyone can drive mobigym.
4. Mobigym can go anywhere, anytime and it can be use of any age.

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