

# Implementation of Three Level Integrated AC-DC Converter with Pulse Width Modulation

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**Abstract—** In this paper, implementation of three-level integrated ac–dc converter with pulse width modulation is presented. The proposed converter combines with the operation of the boost power factor correction and the three-level dc–dc converter. The converter is made to operate with two independent controllers which are combined in a single converter. Input controller does PFC and regulates dc bus, output controller regulates the output voltage. Converter operation is explained and power factor is improved in this paper. Finally the efficiency of the new converter is compared with that of previously proposed converter.

**Keywords—**AC-DC converters, PWM (Pulse Width Modulation), Three level converters, PFC(power factor correction),single stage converters.

## I. INTRODUCTION

Advancement in the research of Power electronic converter is still increasing with the rapid demands in the industry. In search of better efficiency, cost, design flexibility, low harmonics in converters, many converters had been proposed so far. Besides multilevel converters plays a major role in increasing demands. Mostly the AC-DC converters are implemented with PFC to comply with harmonic standards like IEC 1000-3-2[1].Based on this; PFC methods are of two types namely passive and active methods. Passive methods are simple and inexpensive which uses L&C components to filter low frequency input current harmonics & shapes input current to improve power factor. But this makes the converter huge and bulky in size which is less preferred. Due to this active PFC are used nowadays..

Active PFC methods can be implemented either two stage or single stage approach. Two stage converters uses two controllers i.e. one controller for PFC and another controller for output regulation. This method gives poor efficiency in light loads, more losses & expensive too. But it is cost effective for higher power applications. In single stage converters it uses single controller for both PFC and regulation of output voltage. It is used for fast regulation of output voltage which works on steady state. On the analysis of previously proposed converters like voltage fed, current fed and resonant converters, some of their drawbacks are:

1) In current fed converters boost inductors are used at the input of full bridge converters. This gives close to unity power factor but it may lead to high voltage overshoots across the dc

bus voltage due to lack of energy store capacitors. Besides it also results in large low frequency 120 Hz ripple output voltage [13].

2) The resonant converters are good as overall but controlled by varying switching frequency [17],[18]. This makes difficult to design especially their magnetic components as it must operate with wide switching frequency.

3) In voltage fed single stage converters ,they have large energy storage capacitors connected across the primary of dc bus and it prevents voltage overshoots .It also prevents the 120 Hz component from output voltage. By doing so, it eliminates the problem faced by current fed and resonant converters. The converters are made to operate with an output inductor current to prevent the dc-bus voltage from becoming excessive. Still voltage fed converters may suffer from problems of excessive dc bus voltage under high input & low output load due to single controller. Doing so results in the need for components that can handle high peak currents and additional output filtering to remove ripple [12-14].

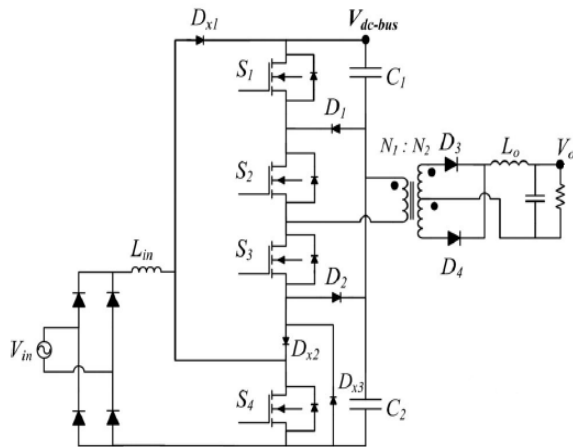
There is need of converter which solves previous problems like excessive dc bus voltage due to lack of dedicated controller, large output ripple, distorted input currents, design flexibility and in terms of cost factor. Considering all this a three level integrated converter has been proposed which uses the multilevel concept [15][16]. With multilevel topologies, the dc bus voltage can be allowed to reach higher levels that are possible with a two-level topology as the converter components are exposed to half the dc bus voltage and, thus, have half the voltage stress. Freeing up the allowable limit of dc bus voltage allows the aforementioned limitations on output and input currents to be eased so that the converter can be made to operate with an output current that has less ripple and an input current that is less distorted than that of a two-level converter.

## II. PULSE WIDTH MODULATION

The proposed converter is made to operate with the PWM technique. PWM signals are pulse trains which are applied to the gate of switches to perform the operation of converter. The pulse trains are fixed frequency and magnitude and variable pulse width. There is one pulse of fixed magnitude in every PWM period. But the width of the pulses changes from period to period according to a modulating signal. When a PWM

signal is applied to the gate of a power transistor, it causes the turn on and turns off intervals of the transistor to change from one PWM period to another PWM period according to the same modulating signal & consequently working of converter starts. The frequency of a PWM signal must be much higher than that of the modulating signal, the fundamental frequency, such that the energy delivered to the load depends mostly on the modulating signal. The control of output voltage is done using pulse width modulation. The commonly used techniques are

1. Single pulse width modulation.
2. Multiple pulse width modulation.
3. Sinusoidal pulse width modulation.
4. Modified sinusoidal pulse width modulation.
5. Phase displacement control



.Fig 1: Proposed converter

### III. CONVERTER OPERATION

The input controller consists of boost inductor  $L_{in}$ , boost diode  $D_{x1}$  & switch  $S_4$  which is shared by multilevel dc-dc section. It performs PFC & regulates primary of dc bus capacitors by sending appropriate signals to  $S_4$  which is done by controlling  $D_2$  & then adding the duty cycle of  $D_2$  to  $D_1$  ( $D_1$  &  $D_2$  are shown in fig 2). Besides regulation of dc bus voltage is done by sending gate signals to  $S_1$  to  $S_4$  by controlling duty cycle of  $D_1$ . In short  $S_4$  perform two tasks ( $D_1$ ) participate in control of output voltage and other part ( $D_2$ ) regulate dc bus voltage. The switches  $S_2$  and  $S_3$  are ON for half a switching cycle, but are never ON at the same time. In the figure the diode rectifier bridge output is replaced by a rectified sinusoidal source ( $V_{rec}$ ) and the thick lines represent the paths of current conduction.

The proposed converter has eight modes of operations:

1) Mode 1 ( $t_0 \leq t \leq t_1$ ) [fig 3(a)]: During this mode, switches  $S_1$  and  $S_2$  are ON and energy from dc-bus capacitor  $C_1$  is transferred to the output load. In the output section, a positive voltage of ( $V_{pri}/n$ )  $-V_o$  (where  $n$  is the ratio of

primary to secondary transformer turns) is impressed across  $L_o$  and the current through it rises.

2) Mode 2 ( $t_1 \leq t \leq t_2$ ) [fig 3(b)]: In mode 2,  $S_1$  and  $S_2$  remain ON and  $S_3$  turns ON. The energy from dc bus capacitor  $C_1$  is transferred to the output load. At the same time, the diode bridge output voltage ( $V_{rec}$ ) is impressed across input inductor  $L_{in}$  so that the current flowing through this inductor rises.

3) Mode 3 ( $t_2 \leq t \leq t_3$ ) [fig 3(c)]: In mode 3,  $S_1$  and  $S_2$  remain ON and  $S_3$  turns ON. The energy from dc-bus capacitor  $C_1$  is transferred to the output load. At the same time, the diode bridge output voltage  $V_{rec}$  is impressed across input inductor  $L_{in}$ , so that the current flowing through this inductor rises.

4) Mode 4 ( $t_3 \leq t \leq t_4$ ) [fig 3 (d)]: In mode 4,  $S_1$  and  $S_2$  are OFF and  $S_4$  is ON. The current in the primary of the transformer charges capacitor  $C_2$  through the body diode of  $S_3$  and  $D_{x3}$ .

5) Mode 5 ( $t_4 \leq t \leq t_5$ ) [fig 3(e)]: In mode 5,  $S_3$  and  $S_4$  are ON. Energy flows from capacitor  $C_2$  flows into the load while the current flowing through input inductor  $L_{in}$  continues to rise.

6) Mode 6 ( $t_5 \leq t \leq t_6$ ) [Fig 3(f)]: In mode 6,  $S_4$  turns off. The current in input inductor flows through the diode  $D_{x1}$  to charge the capacitors  $C_1$  and  $C_2$ . The current in the transformer primary flows through the  $S_3$  and  $D_2$ . This mode ends when the inductor current reaches zero. Also during this mode, the load inductor current freewheels in the secondary of the transformer.

7) Mode 7 ( $t_6 \leq t \leq t_7$ ) [Fig 3(g)]: In mode 7, the load inductor current freewheels in the secondary of the transformer. This mode ends when the switches  $S_3$  turns off.

8) Mode 8 ( $t_7 \leq t \leq t_8$ ) [Fig 3(h)]: In mode 8,  $S_3$  is OFF and the current in the primary of the transformer charges capacitor  $C_1$  through the body diodes of  $S_1$  and  $S_2$ . Finally, converter re-enters Mode 1.

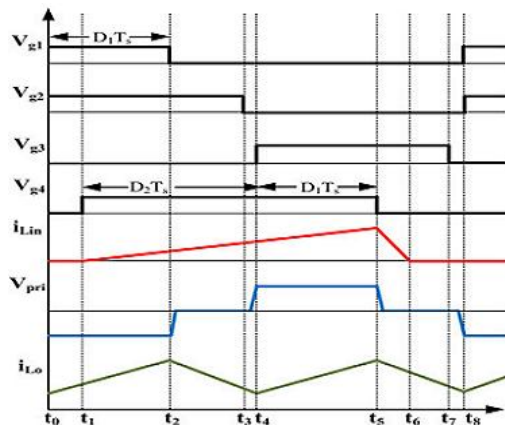


Fig 2: Waveforms explaining of operation of converter.

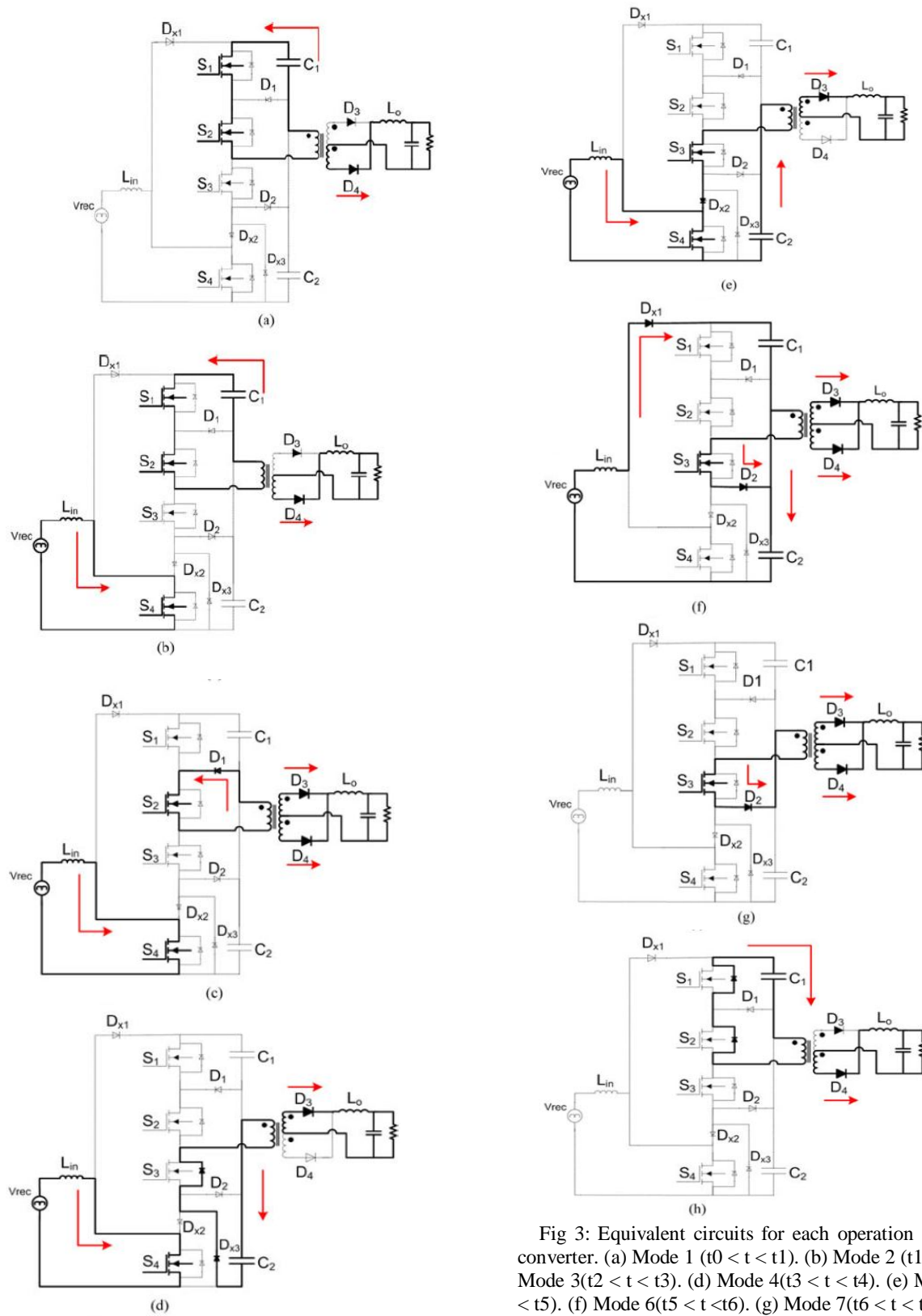


Fig 3: Equivalent circuits for each operation stage for the converter. (a) Mode 1 ( $t_0 < t < t_1$ ). (b) Mode 2 ( $t_1 < t < t_2$ ). (c) Mode 3 ( $t_2 < t < t_3$ ). (d) Mode 4 ( $t_3 < t < t_4$ ). (e) Mode 5 ( $t_4 < t < t_5$ ). (f) Mode 6 ( $t_5 < t < t_6$ ). (g) Mode 7 ( $t_6 < t < t_7$ ). (h) Mode 8 ( $t_7 < t < t_8$ )

#### IV. SIMULATION DIAGRAM OF PROPOSED CONVERTER

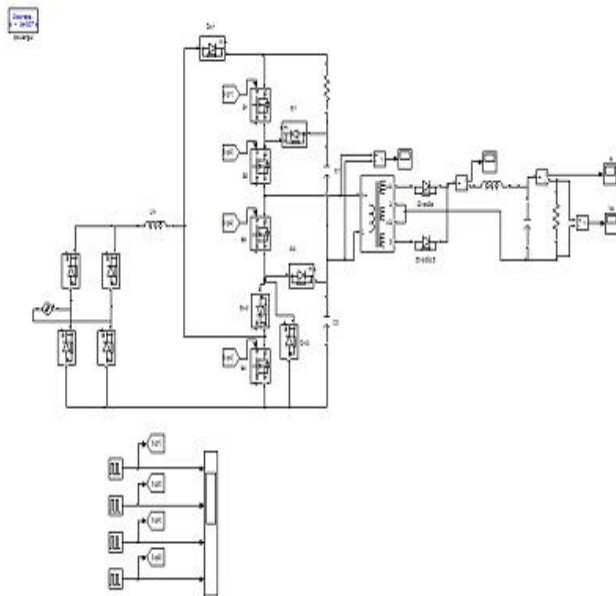


Fig 4: Simulation diagram of Converter.

#### V. RESULTS AND DISCUSSION

It is assumed that the input current is discontinuous, the decoupling of the input controller and output controller can occur because the crossover frequencies of the two loops are very different. The crossover frequency of the input controller is much lower than that of the output controller, which converts the intermediate dc-bus voltage into the desired output voltage. As the two crossover frequencies are far apart, it is therefore possible to consider the design of one controller to be separate from that of the other. Since the two controllers are decoupled, the standard designs for an ac–dc boost converter controller and a dc–dc full-bridge converter controller can also be used.

The proposed converter has the following advantages:

- 1) Reduced cost: The converter is cheaper than a conventional two-stage converter. Replacing a switch and its associated gate drive circuitry with four diodes reduces cost considerably even though the component count seems to be increased.
- 2) Better performance: The proposed single-stage converter can operate with a better input power factor for universal input line applications than a single-controller, single-stage because it does have a dedicated controller for its input section that can perform PFC and regulate the dc-bus voltage. The presence of a second controller also allows the converter to operate with better efficiency and with less output ripple as each section.
- 3) Improved light-load efficiency: The proposed converter can be designed so that it has a conventional dc-bus voltage of 400 V. As the converter is a multilevel converter, a 400 V dc bus means that each switch will be exposed to a maximum

voltage of 200 V. Doing so results in 75% reduction in turn on losses when the converter is operating under light-load conditions.

4) Increased design flexibility: As converter is a multilevel converter, it can also be operated with high dc-bus voltage (800V), standard dc-bus voltage (400V), or any dc-bus voltage  $400V < V_{bus} < 800$ . There is flexibility in the level that the dc-bus voltage is set means that there is considerable flexibility in the design of the converter. But it will have lower heavy-load efficiency because of increased conduction losses as switch S4 must conduct both the input current and the full-bridge current. As a result, when determining whether to use the proposed converter versus a conventional two-stage converter, the main tradeoff that needs to be considered is lower cost and improved light-load efficiency versus heavy-load efficiency.

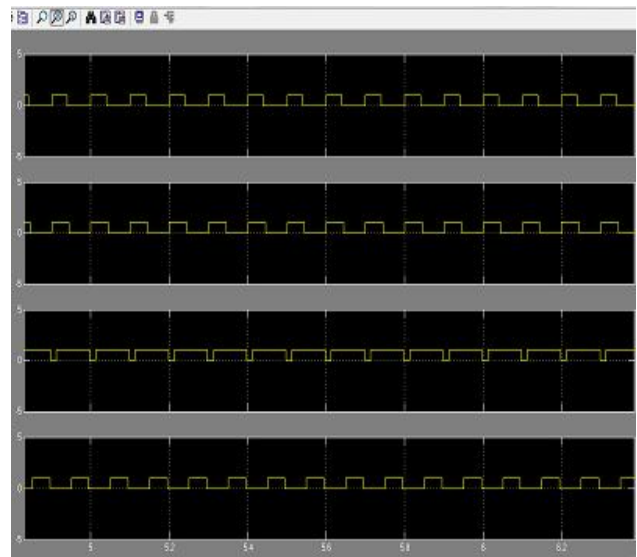


Fig 5: PWM used in simulation circuit. (S1, S2, S4 & S3)

Value for Output Inductor ( $L_o$ ):

$$L_{o,\min} \geq \frac{V_o^2}{0.5 P_{o,\max}} \frac{1 - D_m}{2} \frac{T_{SW}}{2}$$

Value for Inductor ( $L_{in}$ ):

$$L_{in,\max} < \frac{[(V_{bus,\min})]^2 * D_{\max} * (1 - D_{\max})^2}{2P_{o,\max} f_{SW}}$$

Where,  $f_{SW}$ = switching frequency,

D=duty cycle,

$P_o$ = output power,  $T_{sw}$ =switching time,  $V_o$ =output voltage,  
 $V_{bus}$ =dc bus voltage.

The output waveforms based on the simulation results are given as following of the converter can be made to operate in an optimal manner.

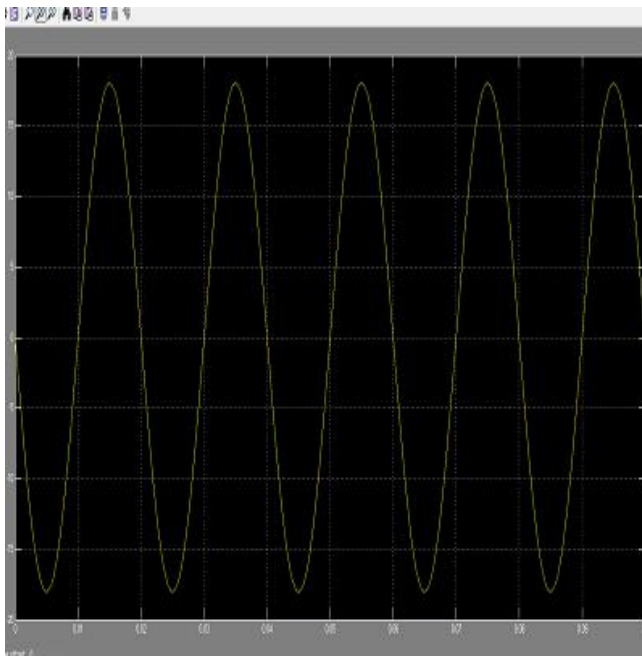


Fig 6: Input current waveforms.

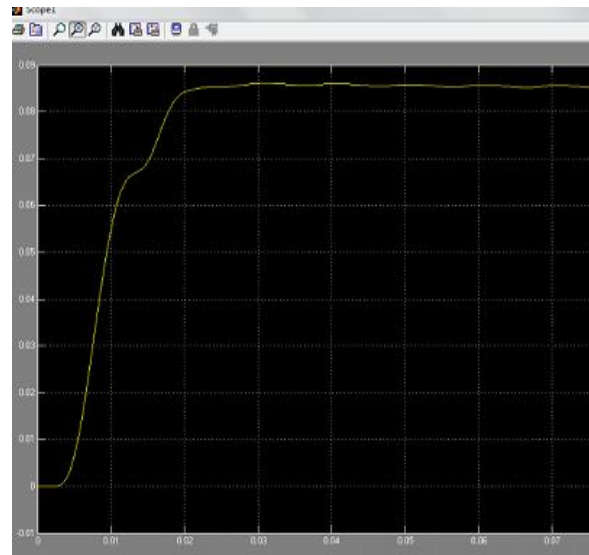


Fig 8: Output current after filtering

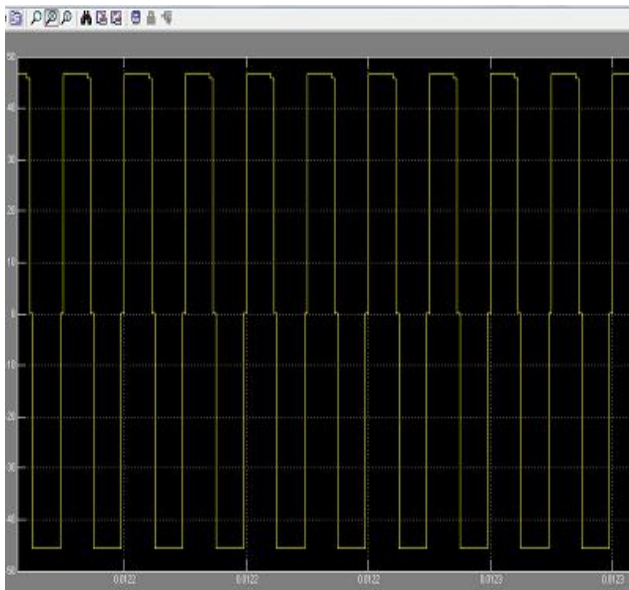


Fig 7: Three level output at of inverter (at the primary of transformer)

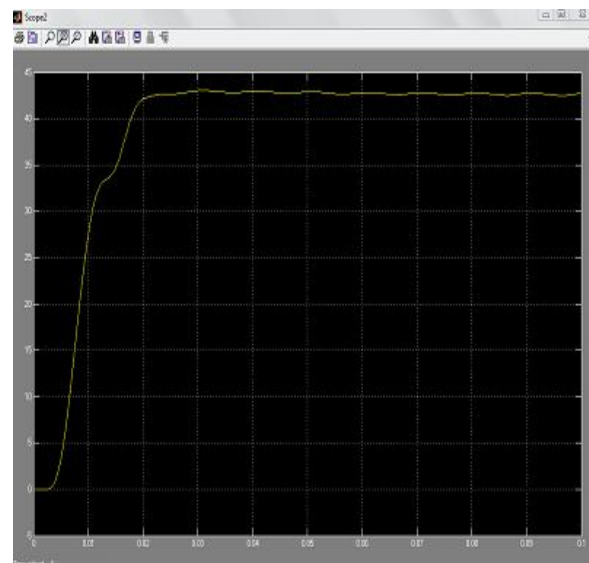


Fig 9: Output voltage

## VI. CONCLUSION

A new single-stage ac–dc converter is proposed in the paper. This converter is operated with two controllers, one controller that performs input PFC and a second controller that regulates the output voltage. The specific feature of this converter is that it combines the performance of two-stage converters with the reduction of cost of single-stage converters. Besides design complexity also much reduced unlike resonant converters. This converter provides constant output voltage with improved power factor. This allows for greater flexibility in the design of the converter and ultimately improved performance. Experimental results that confirm the feasibility of the converter.

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